

BEFORE THE CONTINUUM LIMIT

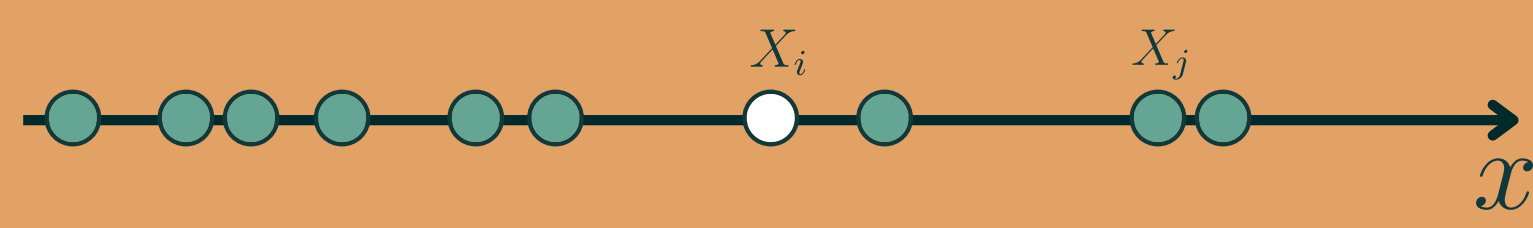
QUANTIFYING FLUCTUATIONS IN PARTICLE MODELS FOR COLLECTIVE MOTION

CONTEXT

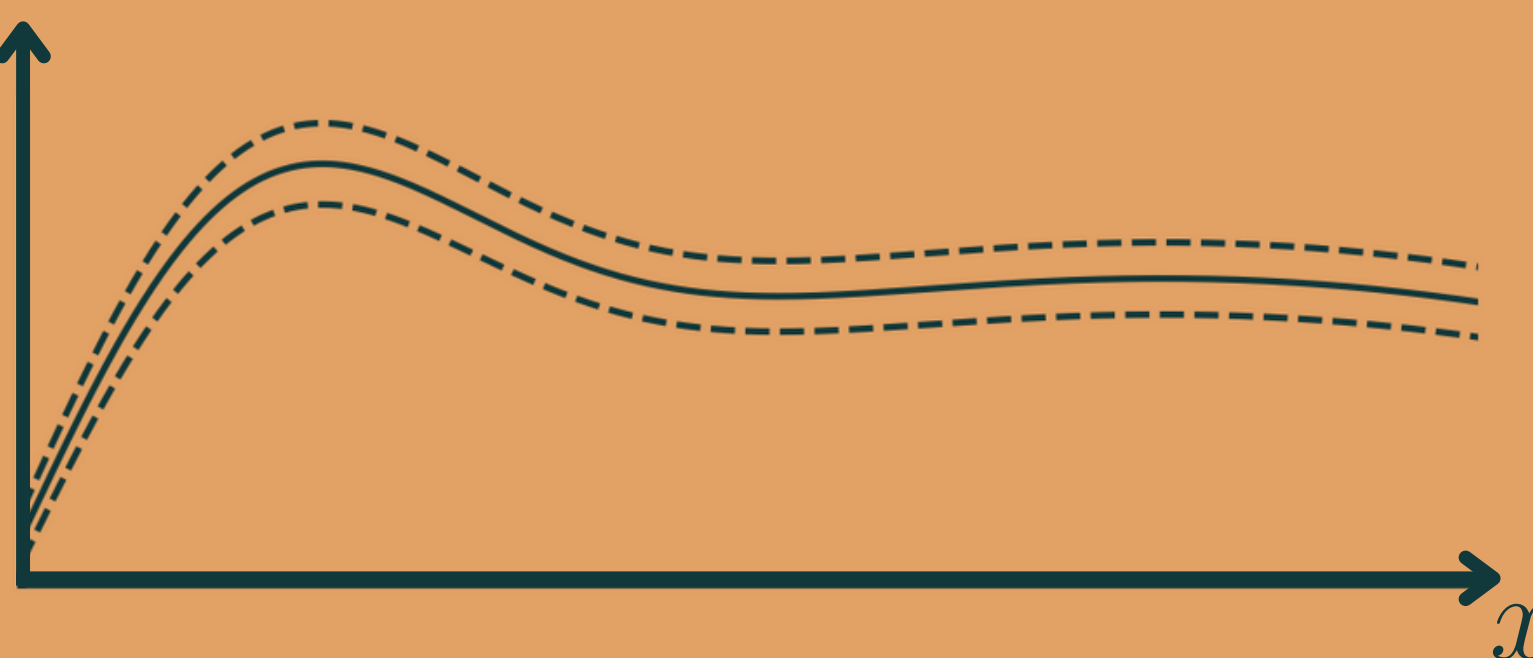
- When studying collective motion, we often consider an infinite number of individuals.
- In reality, particle number is **finite**
- How can we model large but finite numbers of individuals and retain stochastic effects?
- Finite particle effects can produce measureable patterns in the fluctuations

METHODS

- 1 Start from individual, random particles



End with smooth, stochastic density



- 2 Statistically, both formulations behave the same but the latter allows us to find exact results

We study N **Brownian** particles with positions: X_i
They interact with each other through a random and a deterministic coupling function

$$dX_i = \frac{1}{N} \sum_{j=1}^N f(X_i - X_j)dt + \frac{\sqrt{2D}}{N} \sum_{j=1}^N g(X_i - X_j)dW_j(t),$$

- 1 We can write this as an equation for the stochastic density: $\rho(x, t) = \frac{1}{N} \sum_{n=1}^N \delta(x - X_n)$

$$\partial_t \rho = \underbrace{\partial_x (\rho (f * \rho)) + D \partial_x^2 (\rho (g * \rho)^2)}_{\text{Deterministic contribution}} + \underbrace{\sqrt{\frac{2D}{N}} \partial_x (\sqrt{\rho} (g * \rho) \eta)}_{\text{Stochastic term}} \quad \eta: \text{spatiotemporal white noise}$$

- 2 By choosing suitable functions, F_k , we can determine analytic results for fluctuations, ξ_k , about the deterministic limit, ρ^* :

$$\langle \rho, F \rangle = \int_A \rho(x, t) F(x) dx = \frac{1}{N} \sum_{n=1}^N F(X_n)$$

$$\xi_k(t) = \sqrt{N} (\langle \rho, F_k \rangle - \langle \rho^*, F_k \rangle)$$

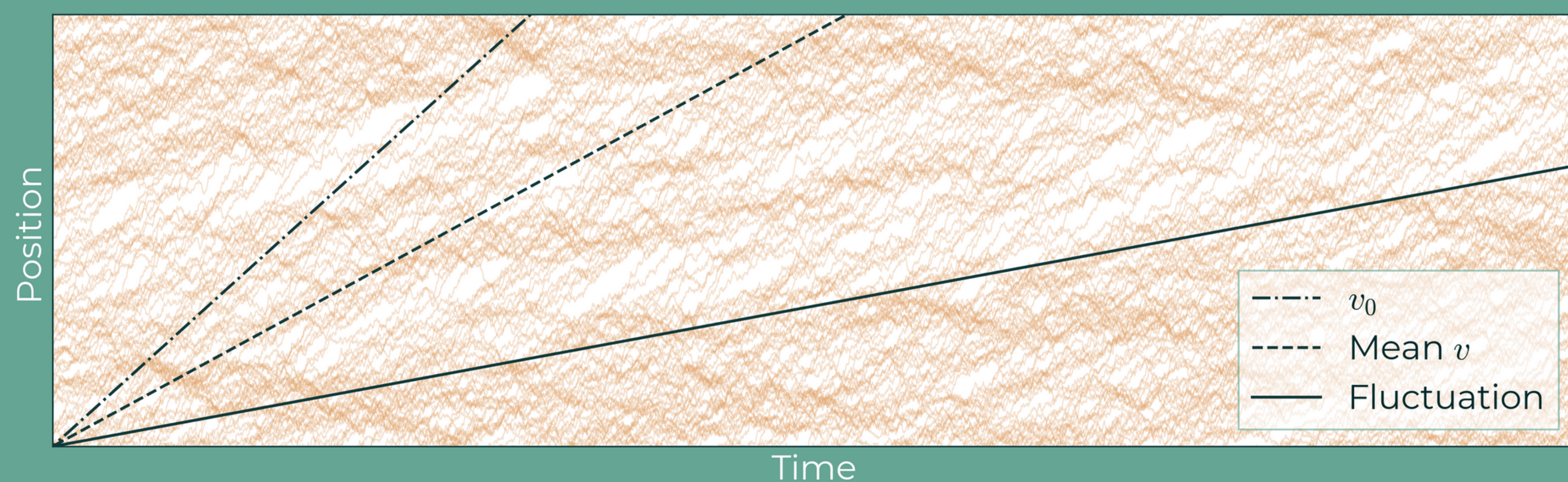
PHANTOM TRAFFIC JAMS

- Traffic jams travel slower than average vehicle velocity, moving backwards relative to the cars.
- Can use the general model to reproduce a continuum model of traffic
- Continuum model predicts stable flow of traffic
- Observe **stochastic waves** of density resembling phantom jams using **Fourier series**:

$$F_k = e^{-ikx}$$

$$\begin{aligned} f(x) &= v_0(1 - \delta(x)/\rho_{\text{jam}}) \\ g(x) &= 1 \end{aligned} \Rightarrow \partial_t \rho + \partial_x (\rho v_0(1 - \rho/\rho_{\text{jam}})) = D \partial_x^2 \rho$$

↑ max velocity ↑ max density



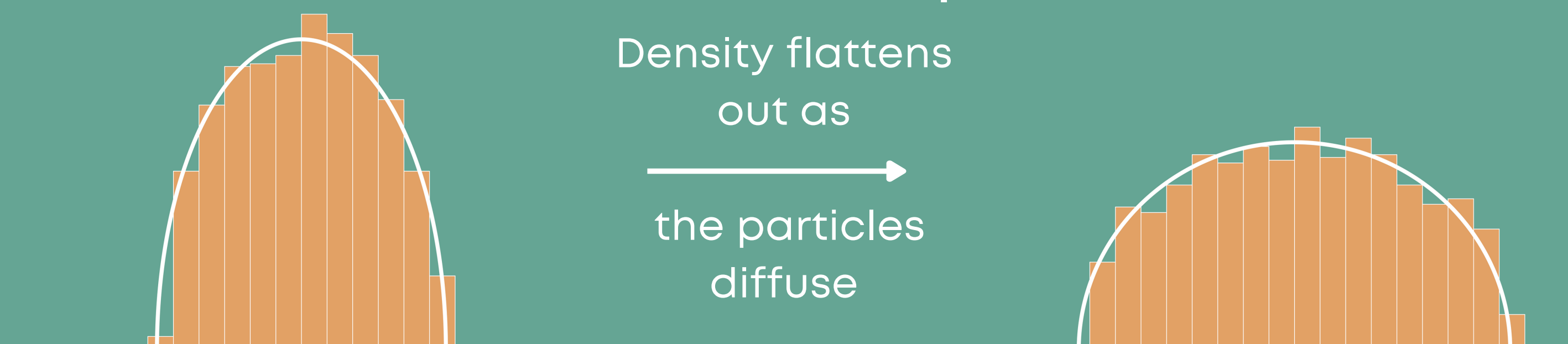
NONLINEAR DIFFUSION

- Organisms do not always diffuse independently.
- We can model density dependent diffusion using the general model with a Dirac delta
- How much do we expect the centre to move?
- How much will the general shape change?

$$g(x) = \delta(x) \Rightarrow \partial_t \rho = D \partial_x^2 (\rho^3)$$

$$F_k = x^k$$

- Deterministic solution is an ellipse flattening over time.
- Find the variances in the **centre of mass & mean squared displacement**
- Characterise the fluctuations about the **cumulative moments**:



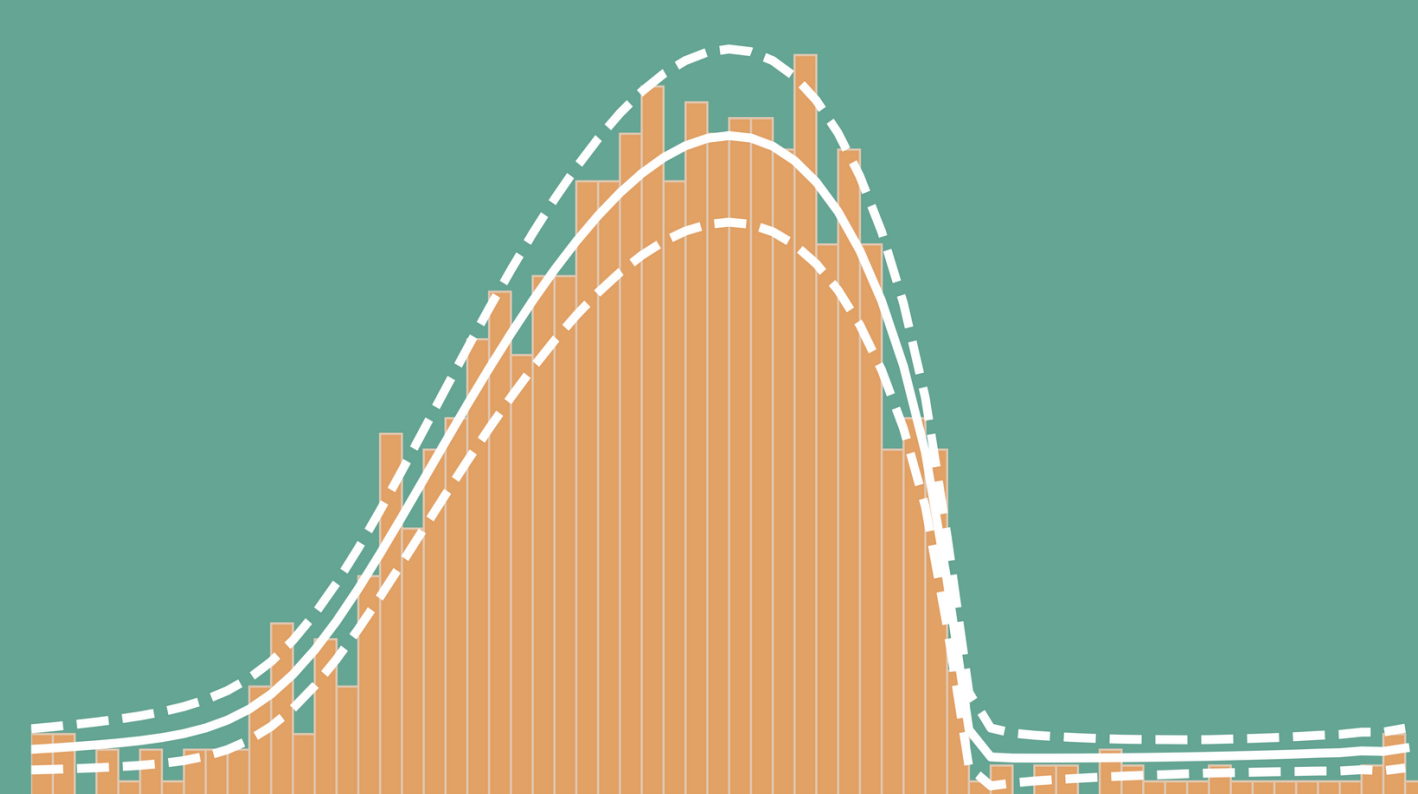
SWARMING OF ORGANISMS

- Consider organisms which try to catch up with others in front of them
- They diffuse more when they are very close to others to maintain reasonable distance.
- Study fluctuations in discretised elements, $k = 1, \dots, M$

$$F_k = \mathbf{1}_{[\frac{k-1}{M}, \frac{k}{M}]}$$

$$\begin{aligned} f(x) &= H(x)e^{-x} \\ g(x) &= \delta(x) \end{aligned} \quad H(x) \text{ Heaviside function}$$

- Calculate the covariance of elements in this discretised version.



Swarm of organisms moving right with predicted variation in shape.

- Solitary waves form but there is no closed form solution for the deterministic limit.
- Instead, Use a numerical solution of the discretised equation: ρ^*

SYNCHRONISATION

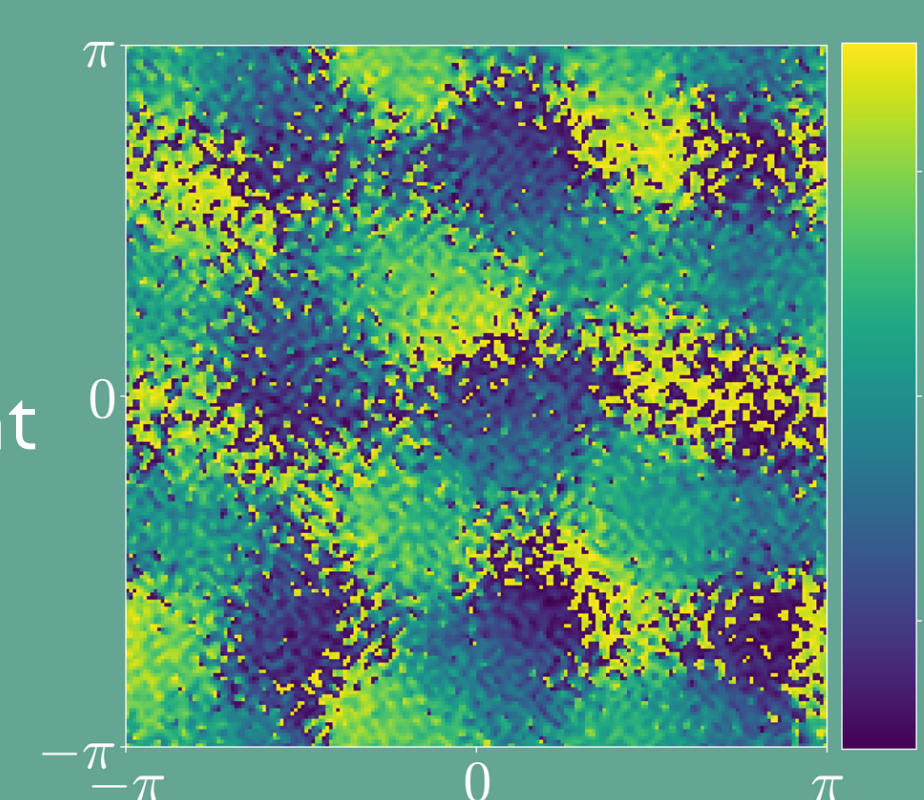
- In the Kuramoto model: oscillators which try to align their phase.
- We added a non local coupling in space to a lattice of oscillators

$$d\vartheta_n = \frac{1}{N} \sum_{m=1}^N K(\vec{x}_n - \vec{x}_m) \sin(\vartheta_n - \vartheta_m) dt + \sqrt{2D} dW_n(t)$$

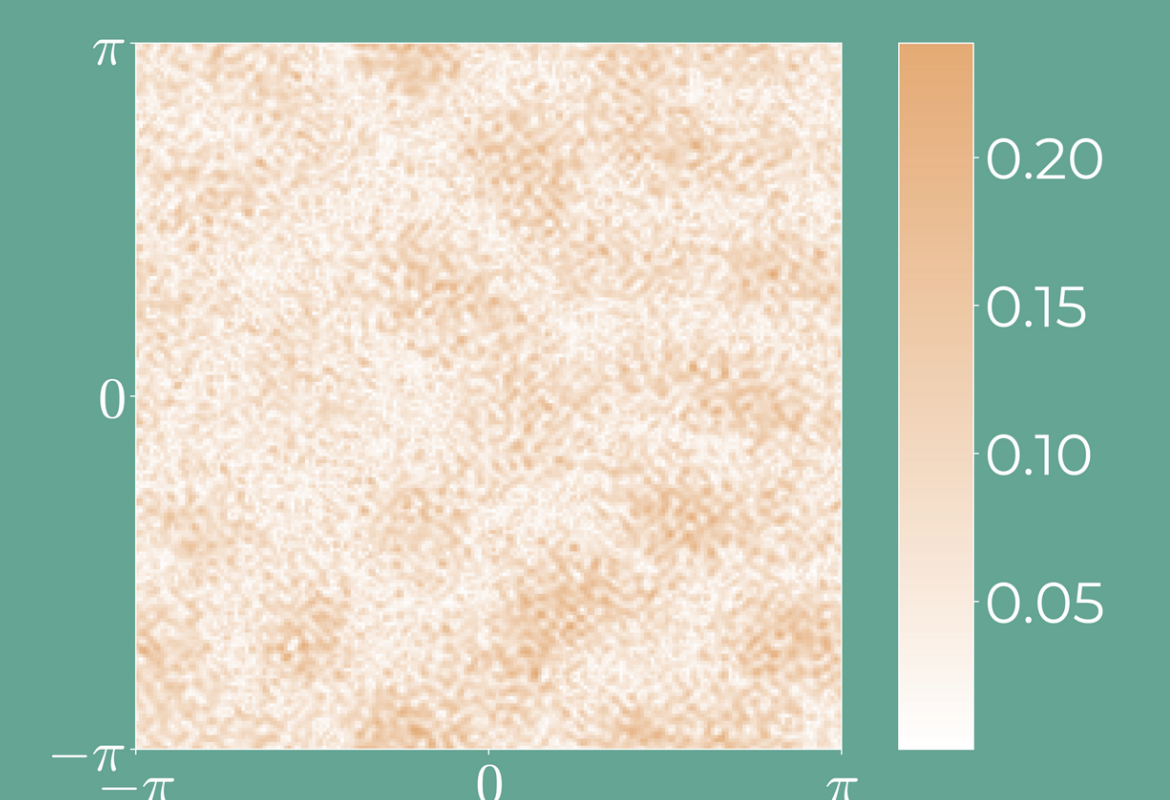
- **Continuum limit** predicts no patterns
- Stochastic patterns with spatial structure quantified by fluctuations in Fourier Series:

$$F_k = e^{-i(k \cdot \vec{x} + \vartheta)}$$

Left: $\arg(\xi(\vec{x}))$
mean phase of oscillators at each lattice point



Right: $|\xi(\vec{x})|$
coherence



REFERENCES, PREPRINT, AND POSTER PDF AVAILABLE HERE!

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